

# ICCRE 2025 10th International Conference on CONTROL AND ROBOTICS ENGINEERING



May 9-11, 2025

Conference Venue: Nagoya, Japan  
(Aichi Industry & Labor Center (WINC AICHI))

Co-Sponsored by: Hohai University, China; IEEE; IEEE Robotics and Automation Society

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Website: [www.iccre.org](http://www.iccre.org)

## Publication: IEEE Conference Proceedings

Accepted papers after proper registration and presentation, will be published in the ICCRE 2025-IEEE Conference Proceedings.

ICCRE 2025 has been listed on the IEEE conference list!  
[https://conferences.ieee.org/conferences\\_events/conferences/conferencedetails/65455](https://conferences.ieee.org/conferences_events/conferences/conferencedetails/65455)



## ICCRE History

ICCRE 2024 ISBN: 979-8-3503-7268-7 IEEE Xplore | Ei Compendex and Scopus  
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## Submission Information

1. Submission link: <https://easychair.org/conferences/?conf=iccre2025>
2. Submission email: [iccre@vip.163.com](mailto:iccre@vip.163.com)
3. Template:  
Full paper: <http://www.iccre.org/IEEE-Formatting.doc>  
Abstract: <http://www.iccre.org/Abstract-Template.doc>  
(Full paper means presentation and publication, abstract means presentation only, without publication)
4. Submission Deadline: January 20, 2025

## Keynote Speaker



Prof. Shugen Ma  
The Hong Kong University of Science and Technology (Guangzhou), China

Prof. Makoto Iwasaki  
Nagoya Institute of Technology, Japan



Prof. Tong Heng LEE  
National University of Singapore, Singapore

Prof. Xingjian Jing  
City University of Hong Kong, Hong Kong

## Contacts Us

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## Submission Topics

Looking for more topics, please visit at <http://www.iccre.org/cfp.html>

### Control Science and Engineering

Adaptive control  
Robust control  
Process control  
Complex systems  
Co-operative control

### Robotics Science and Engineering

Modeling and identification  
Robot control  
Mobile robotics  
Mobile sensor networks  
Micro robots and micro-manipulation

### Vision Science and Engineering

Image/video analysis  
Scene analysis  
Pattern recognition  
Learning in vision

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