

ICCRE 2025 10th International Conference on CONTROL AND ROBOTICS ENGINEERING



May 9-11, 2025

Conference Venue: Nagoya, Japan
(Aichi Industry & Labor Center (WINC AICHI))

Co-Sponsored by: Hohai University, China; IEEE; IEEE Robotics and Automation Society

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Publication: IEEE Conference Proceedings

Accepted papers after proper registration and presentation, will be published in the ICCRE 2025-IEEE Conference Proceedings.

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Submission Information

1. Submission link: <https://easychair.org/conferences/?conf=iccre2025>
2. Submission email: iccre@vip.163.com
3. Template:
Full paper: <http://www.iccre.org/IEEE-Formatting.doc>
Abstract: <http://www.iccre.org/Abstract-Template.doc>
(Full paper means presentation and publication, abstract means presentation only, without publication)
4. Submission Deadline: January 20, 2025

Keynote Speaker



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The Hong Kong University of Science and Technology (Guangzhou), China

Prof. Makoto Iwasaki
Nagoya Institute of Technology, Japan



Prof. Tong Heng LEE
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Adaptive control
Robust control
Process control
Complex systems
Co-operative control

Robotics Science and Engineering

Modeling and identification
Robot control
Mobile robotics
Mobile sensor networks
Micro robots and micro-manipulation

Vision Science and Engineering

Image/video analysis
Scene analysis
Pattern recognition
Learning in vision

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